

**CSC 405**  
**Introduction to Computer Security**  
**Reverse Engineering**

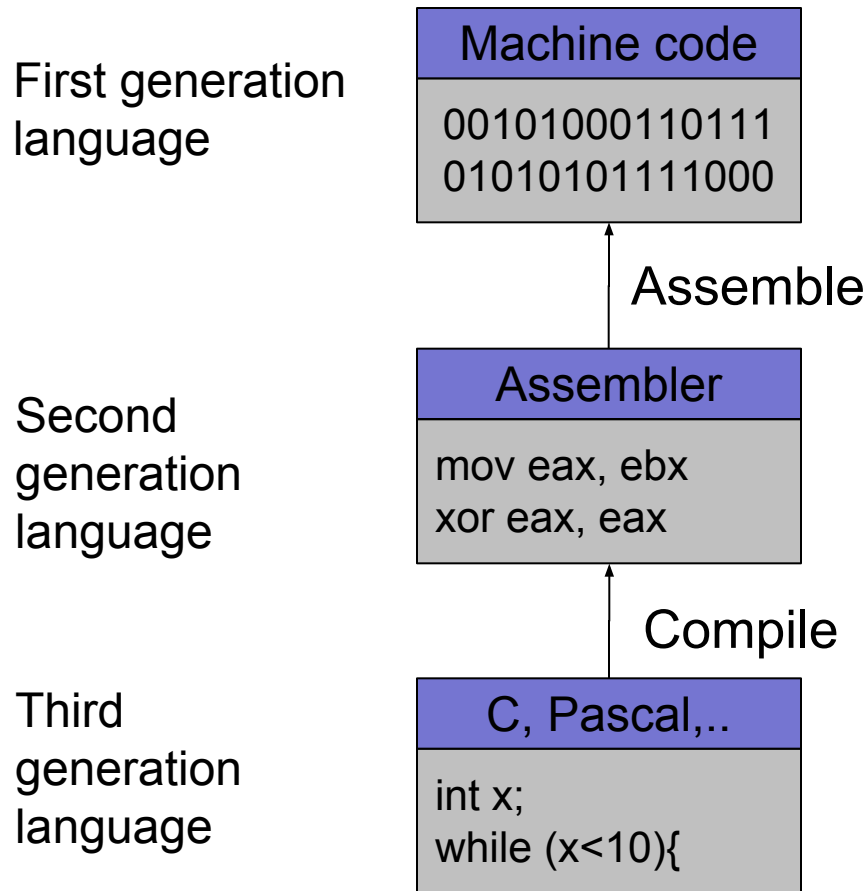
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(Derived from slides by Chris Kruegel)

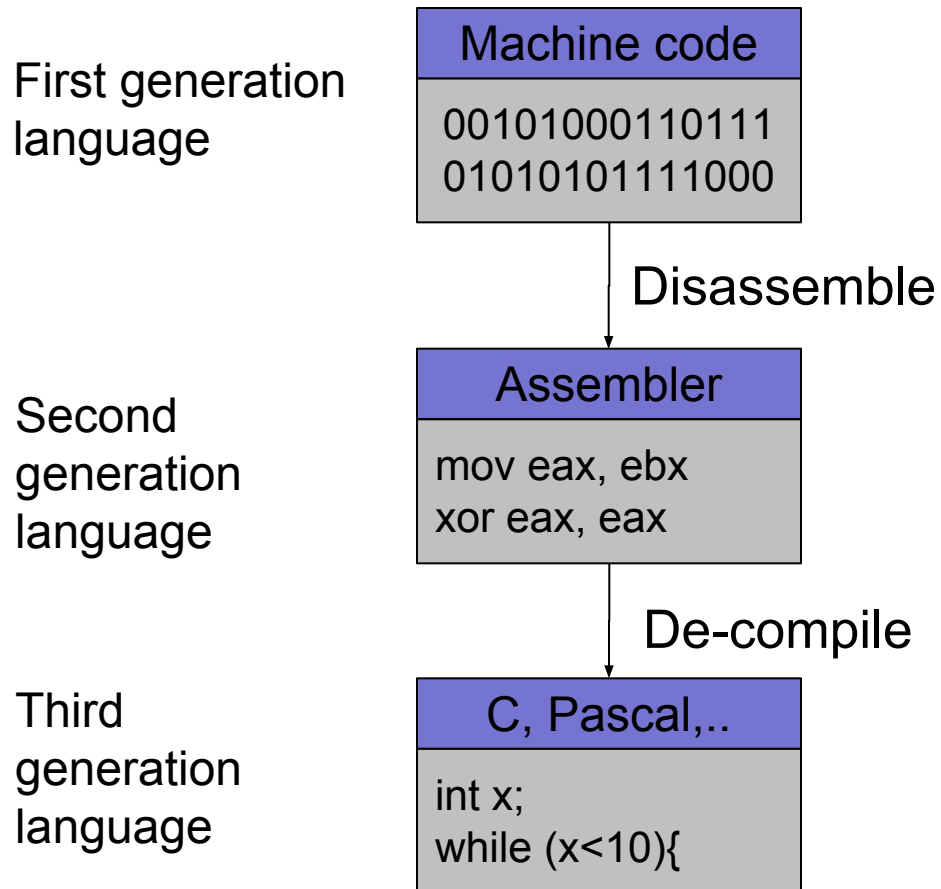
# Introduction

- Reverse engineering
  - process of analyzing a system
  - understand its structure and functionality
  - used in different domains (e.g., consumer electronics)
- Software reverse engineering
  - understand architecture (from source code)
  - extract source code (from binary representation)
  - change code functionality (of proprietary program)
  - understand message exchange (of proprietary protocol)

# Software Engineering



# Software Reverse Engineering



# Going Back is Hard!

- Fully-automated disassemble/de-compilation of arbitrary machine-code is theoretically an undecidable problem
- Disassembling problems
  - hard to distinguish code (instructions) from data
- De-compilation problems
  - structure is lost
    - data types are lost, names and labels are lost
  - no one-to-one mapping
    - same code can be compiled into different (equivalent) assembler blocks
    - assembler block can be the result of different pieces of code

# Why Reverse Engineering

- Software interoperability
  - Samba (SMB Protocol)
  - OpenOffice (MS Office document formats)
- Emulation
  - Wine (Windows API)
  - React-OS (Windows OS)
- Malware analysis
- Program cracking
- Compiler validation

# Analyzing a Binary

## Static Analysis

- Identify the file type and its characteristics
  - architecture, OS, executable format...
- Extract strings
  - commands, password, protocol keywords...
- Identify libraries and imported symbols
  - network calls, file system, crypto libraries
- Disassemble
  - program overview
  - finding and understanding important functions
    - by locating interesting imports, calls, strings...

# Analyzing a Binary

## Dynamic Analysis

- Memory dump
  - extract code after decryption, find passwords...
- Library/system call/instruction trace
  - determine the flow of execution
  - interaction with OS
- Debugging running process
  - inspect variables, data received by the network, complex algorithms..
- Network sniffer
  - find network activities
  - understand the protocol



# Static Techniques

- Gathering program information
  - get some rough idea about binary (`file`)

```
linux util # file sil
sil: ELF 32-bit LSB executable, Intel 80386, version 1
(SYSV), for GNU/Linux 2.6.9, dynamically linked (uses s
hared libs), not stripped
```

- strings that the binary contains (`strings`)

```
linux util # strings sil | head -n 5
/lib/ld-linux.so.2
_Jv_RegisterClasses
__gmon_start__
libc.so.6
puts
```

# Static Techniques

- Examining the program (ELF) header (`elfsh`)

```
[ELF HEADER]
[Object sil, MAGIC 0x464C457F]

Architecture      :      Intel 80386      ELF Version      :      1
Object type       :      Executable object SHT strtab index :      25
Data encoding     :      Little endian    SHT foffset     :      4061
PHT foffset       :      52               SHT entries number :      28
PHT entries number :      8               SHT entry size   :      40
PHT entry size    :      32               ELF header size  :      52
Entry point       :      0x8048500        [_start]
{PAX FLAGS = 0x0}
PAX_PAGEEXEC     :      Disabled          PAX_EMULTRAMP   :      Not emulated
PAX_MPROTECT     :      Restricted        PAX_RANMMAP     :      Randomized
PAX_RANDEXEC     :      Not randomized    PAX_SEGMEEXEC   :      Enabled
```

Program entry point



# Static Techniques

- Used libraries

- easier when program is dynamically linked (ldd)

Interesting “shared” library

–

used for (fast) system calls

```
linux util # ldd sil
linux-gate.so.1 => (0xffffe000)
libc.so.6 => /lib/libc.so.6 (0xb7e99000)
/lib/ld-linux.so.2 (0xb7fcf000)
```

- more difficult when program is statically linked

```
linux util # gcc -static -o sil-static simple.c
linux util # ldd sil-static
not a dynamic executable
linux util # file sil-static
sil-static: ELF 32-bit LSB executable, Intel 80386, version 1
(SYSV), for GNU/Linux 2.6.9, statically linked, not stripped
```

# Static Techniques

## Looking at linux-gate.so.1

```
linux util # cat /proc/self/maps | tail -n 1
ffffe000-ffffff00 r-xp 00000000 00:00 0 [vdso]
linux util # dd if=/proc/self/mem of=linux-gate.dso bs=4096 skip=1048574
count=1 2> /dev/null
linux util # objdump -d linux-gate.dso | head -n 11
```

```
linux-gate.dso: file format elf32-i386
```

Disassembly of section .text:

```
ffffe400 <__kernel_vsyscall>:
ffffe400: 51                push   %ecx
ffffe401: 52                push   %edx
ffffe402: 55                push   %ebp
ffffe403: 89 e5             mov    %esp,%ebp
ffffe405: 0f 34             sysenter
```

# Static Techniques

- Used library functions
  - again, easier when program is dynamically linked (`nm -D`)

```
linux util # nm -D sil | tail -n8
          U fprintf
          U fwrite
          U getopt
          U opendir
08049bb4 B optind
          U puts
          U readdir
08049bb0 B stderr
```

- more difficult when program is statically linked

```
linux util # nm -D sil-static
nm: sil-static: No symbols
linux util # ls -la sil*
-rwxr-xr-x 1 root chris 8017 Jan 21 20:37 sil
-rwxr-xr-x 1 root chris 544850 Jan 21 20:58 sil-static
```

# Static Techniques

## Recognizing libraries in statically-linked programs

- Basic idea
  - create a checksum (hash) for bytes in a library function
- Problems
  - many library functions (some of which are very short)
  - variable bytes – due to dynamic linking, load-time patching, linker optimizations
- Solution
  - more complex pattern file
  - uses checksums that take into account variable parts
  - implemented in `IDA Pro` as:
    - Fast Library Identification and Recognition Technology (FLIRT)

# Static Techniques

- Program symbols
  - used for debugging and linking
  - function names (with start addresses)
  - global variables
  - use `nm` to display symbol information
  - most symbols can be removed with `strip`
- Function call trees
  - draw a graph that shows which function calls which others
  - get an idea of program structure

# Static Techniques

## Displaying program symbols

```
linux util # nm sil | grep " T"  
080488c7 T __i686.get_pc_thunk.bx  
08048850 T __libc_csu_fini  
08048860 T __libc_csu_init  
08048904 T _fini  
08048420 T _init  
08048500 T _start  
080485cd T display_directory  
080486bd T main  
080485a4 T usage  
linux util # strip sil  
linux util # nm sil | grep " T"  
nm: sil: no symbols
```



# Static Techniques

- Disassembly
  - process of translating binary stream into machine instructions
- Different level of difficulty
  - depending on ISA (instruction set architecture)
- Instructions can have
  - fixed length
    - more efficient to decode for processor
    - RISC processors (SPARC, MIPS)
  - variable length
    - use less space for common instructions
    - CISC processors (Intel x86)

# Static Techniques

- Fixed length instructions
  - easy to disassemble
  - take each address that is multiple of instruction length as instruction start
  - even if code contains data (or junk), all program instructions are found
- Variable length instructions
  - more difficult to disassemble
  - start addresses of instructions not known in advance
  - different strategies
    - linear sweep disassembler
    - recursive traversal disassembler
  - disassembler can be desynchronized with respect to actual code

# Intel x86 Assembler Primer

- Assembler Language
  - human-readable form of machine instructions
  - must understand the hardware architecture, memory model, and stack
- AT&T syntax
  - mnemonic source(s), destination
  - standalone numerical constants are prefixed with a \$
  - hexadecimal numbers start with 0x
  - registers are specified with %

# Intel x86 Assembler Primer

- Registers

- local variables of processor
- six 32-bit general purpose registers
  - can be used for calculations, temporary storage of values, ...  
`%eax, %ebx, %ecx, %edx, %esi, %edi`
- several 32-bit special purpose registers
  - `%esp` - stack pointer
  - `%ebp` - frame pointer
  - `%eip` - instruction pointer

- Important mnemonics (instructions)

`mov` data transfer

`add / sub` arithmetic

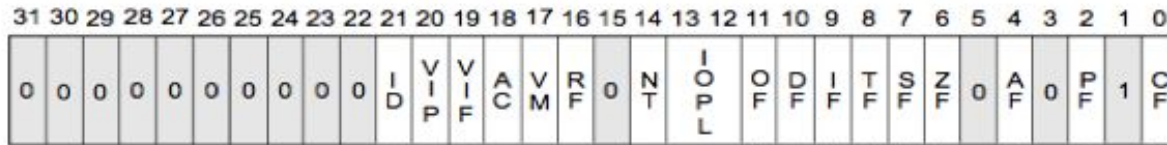
`cmp / test` compare two values and set control flags

`je / jne` conditional jump depending on control flags (branch)

`jmp` unconditional jump

# Intel x86 Assembler Primer

## Status (EFLAGS) Register



- S Indicates a Status Flag
- C Indicates a Control Flag
- X Indicates a System Flag

Reserved bit positions. DO NOT USE.  
Always set to values previously read.

# Intel x86 Assembler Primer

- Status (EFLAGS) Register
  - used for control flow decision
  - set implicit by many operations (arithmetic, logic)
- Flags typically used for control flow
  - CF (carry flag)
    - set when operation “carries out” most significant bit
  - ZF (zero flag)
    - set when operation yields zero
  - SF (signed flag)
    - set when operation yields negative result
  - OF (overflow flag)
    - set when operation causes 2’s complement overflow
  - PF (parity flag)
    - set when the number of ones in result of operation is even

# Intel x86 Assembler Primer

Instruction	Synonym	Jump condition	Description
jmp label		1	direct jump
jmp *operand		1	indirect jump
je label	jz	ZF	equal/zero
jne label	jnz	~ZF	not equal/zero
js label		SF	negative
jns label		~SF	non-negative
jg label	jnle	~(SF ^ OF) & ~ZF	greater than (signed)
jge label	jnl	(~SF ^ OF)	greater or equal (signed)
jl label	jnge	SF ^ OF	less than (signed)
jle label	jng	(SF ^ OF)   ZF	less or equal (signed)
ja label	jnb	~CF & ~ZF	above (unsigned)
jae label	jnb	~CF	above or equal (unsigned)
jb label	jnae	CF	below (unsigned)
jbe label	jna	CF   ZF	below or equal (unsigned)

# Intel x86 Assembler Primer

- When are flags set?
  - implicit, as a side effect of many operations
  - can use explicit compare / test operations
- Compare
  - `cmp b, a` [ note the order of operands ]
  - computes  $(a - b)$  but does not overwrite destination
  - sets ZF (if  $a == b$ ), SF (if  $a < b$ ) [ and also OF and CF ]
- How is a branch operation implemented
  - typically, two step process
    - first, a compare/test instruction
    - followed by the appropriate jump instruction



# Intel x86 Assembler Primer

- Program can access data stored in memory
  - memory is just a linear (flat) array of memory cells (bytes)
  - accessed in different ways (called addressing modes)
- Most general fashion
  - `address: displacement(%base, %index, scale)`  
where the result address is  $\text{displacement} + \%base + \%index * scale$
- Simplified variants are also possible
  - use only displacement → direct addressing
  - use only single register → register addressing

# Intel x86 Assembler Primer

- Stack
  - managed by stack pointer (%esp) and frame pointer (%ebp)
  - special commands (push, pop)
  - used for
    - function arguments
    - function return address
    - local arguments
- Byte ordering
  - important for multi-byte values (e.g., four byte long value)
  - Intel uses *little endian* ordering
  - how to represent `0x03020100` in memory?

<code>0x040</code>	0
<code>0x041</code>	1
<code>0x042</code>	2
<code>0x043</code>	3

# Intel x86 Assembler Primer

```
# no input
# returns a status code, you can view it by typing echo $?
# %ebx holds the return code
.section .text
.globl _start

_start:
movl $1, %eax    # This is the system call for exiting program
movl $0, %ebx    # This value is returned as status
int $0x80      # This interrupt calls the kernel, to execute sys call
```

# Intel x86 Assembler Primer

- So how do we create the application?
  - we need to assemble and link the code
  - this can be done by using the assembler *as* (or *gcc*)

- Assemble

```
as exit.s -o exit.o |  
gcc -c -o exit.o exit.s
```

- Link

```
ld -o exit exit.o |  
gcc -nostartfiles -o exit exit.o
```

# Intel x86 Assembler Primer

- If statement

```
#include <stdio.h>

int main(int argc, char **argv)
{
    int a;

    if(a < 0) {
        printf("A < 0\n");
    }
    else {
        printf("A >= 0\n");
    }
}
```

```
.LC0:
    .string "A < 0\n"

.LC1:
    .string "A >= 0\n"

.globl main
.type   main, @function
main:

    [ function prologue ]
    cmpl    $0, -4(%ebp) /* compute: a - 0 */
    jns     .L2          /* jump, if sign bit
                        not set: a >= 0 */

    movl    $.LC0, (%esp)
    call    printf
    jmp     .L3

.L2:
    movl    $.LC1, (%esp)
    call    printf

.L3:
    leave
    ret
```

# Intel x86 Assembler Primer

- While statement

```
#include <stdio.h>

int main(int argc, char **argv)
{
    int i;

    i = 0;
    while(i < 10)
    {
        printf("%d\n", i);
        i++;
    }
}
```

```
.LC0:
    .string "%d\n"

main:
    [ function prologue ]
    movl    $0, -4(%ebp)

.L2:
    cmpl   $9, -4(%ebp)
    jle    .L4
    jmp    .L3

.L4:
    movl   -4(%ebp), %eax
    movl   %eax, 4(%esp)
    movl   $.LC0, (%esp)
    call  printf
    leal  -4(%ebp), %eax
    incl  (%eax)
    jmp   .L2

.L3:
    leave
    ret
```

# Intel x86 Assembler Primer

## Task: Find the maximum of a list of numbers

- Questions to ask:
  - Where will the numbers be stored?
  - How do we find the maximum number?
  - How much storage do we need?
  - Will registers be enough or is memory needed?
  
- Let us designate registers for the task at hand:
  - %edi holds position in list
  - %ebx will hold current highest
  - %eax will hold current element examined